

MAAD-011036

Rev. V1

Features

- 6-Bit, 0.5 dB LSB, 31.5 dB Range
- Integrated CMOS Driver
- Parallel or Serial (P/S) Control
- Low DC Power Consumption
- Attenuation Accuracy: +/-(0.4 + 7% of attenuation setting) dB
- Lead-Free 4 mm 24-Lead PQFN Package
- RoHS* Compliant

Applications

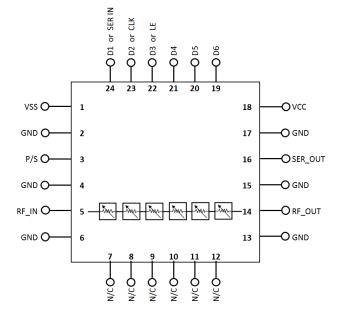
- Test Equipment (instrumentation)
- Communications (commercial and military) : Cellular Infrastructure Radars Radios (MMW)
- General Purpose

Description

The MAAD-011036 is a wide band 6-bit, 0.5 dB step MMIC digital attenuator in a lead-free 4 mm 24 lead PQFN surface mount plastic package. This device is ideally suited for use where high accuracy, very low power consumption, and low intermodulation products are required.

This attenuator is controlled with either a SPI compatible serial interface or a 6 bit parallel word.

Functional Schematic



Pin Configuration^{1,2}

Pin #	Function
1	VSS
2, 4, 6, 13, 15, 17	GND
3	P/S
7 - 12	N/C
5	RF IN
14	RF OUT
16	SER OUT
18	VCC
19	D6
20	D5
21	D4
22	D3 or LE
23	D2 or CLK
24	D1 or SER IN

1. MACOM recommends grounding all N/C (no connection) pins

The exposed pad centered on the package bottom must be connected to RF, DC and thermal ground.

* Restrictions on Hazardous Substances, compliant to current RoHS EU directive.

Package

500 piece reel

Sample Board

Ordering Information
Part Number

MAAD-011036-TR0500

MAAD-011036-001SMB

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Electrical Specifications:

Freq. = 0.1 - 30 GHz, T_A = 25°C, Z_0 = 50 Ω , V_{CC} = +5 V, V_{SS} = -5 V, P_{IN} = 0 dBm

Parameter	Test Conditions	Units	Min.	Тур.	Max.
Reference Insertion Loss ³	0.1 - 18.0 GHz 18.0 - 26.5 GHz 26.5 - 30.0 GHz	dB —		3.6 4.8 5.5	4.8 — 6.7
RMS Attenuation Error ⁴	0.1 - 30.0 GHz (RMS, mean)	dB	dB —		_
Attenuation Accuracy	Relative to Insertion Loss (0.1 - 30 GHz)	± (0.4 + 7% of attenuation setting), typ.			
Return Loss (IN & OUT)	All states	dB	—	-12	—
Input P0.1dB	Reference State (beyond 1 GHz)	dBm	_	23	
IIP ₃	2-Tone, +10 dBm/tone, 1 MHz Spacing Reference State (beyond 1 GHz)	dBm	—	41	_
T _{RISE} , T _{FALL}	10% to 90% RF, 90% to 10% RF	ns	—	15	—
V _{CC}		V	+3.0	-	+5.5
I _{CC}	_	μA	_	5	
V _{SS}	_	V	-5.5	-5.0	-3.0
I _{SS}		mA	_	-0.1	
V _H V _L	HIGH level control voltage LOW level control voltage			_	V _{CC} 0.3 X V _{CC}
ESD	НВМ	V	—	Class 1A	—

3. Test frequencies = 1 GHz, 18 GHz, and 30 GHz.

4. RMS calculation, mean:

RMS ERROR, mean =
$$\frac{1}{n}$$

$$\sqrt{\frac{1}{n}\sum(Er_i-Er_{Ave})^2}$$

Truth Table⁵

D6	D5	D4	D3	D2	D1	Attenuation (dB)
0	0	0	0	0	0	Reference IL
0	0	0	0	0	1	0.5
0	0	0	0	1	0	1
0	0	0	1	0	0	2
0	0	1	0	0	0	4
0	1	0	0	0	0	8
1	0	0	0	0	0	16
1	1	1	1	1	1	31.5

5. "0" = CMOS Low, "1" = COMS High (see specifications table).

Absolute Maximum Ratings^{6,7}

Parameter	Absolute Maximum
Input Power	31 dBm
V _{CC} Voltage	6 V
Control Voltage	-0.5 V <u><</u> V _C <u><</u> 5.5 V
Junction Temperature	+150°C
Operating Temperature	-40°C to +85°C
Storage Temperature	-65°C to +150°C

6. Exceeding any one or combination of these limits may cause permanent damage to this device.

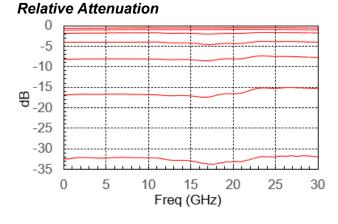
7. MACOM does not recommend sustained operation near these survivability limits.

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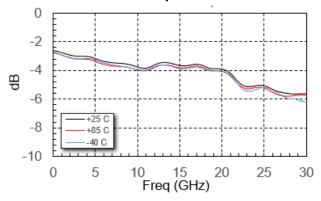


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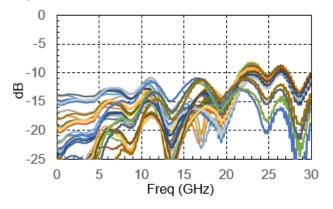
Typical RF Performance Plots, @ +25°C



Insertion Loss vs. Temperature

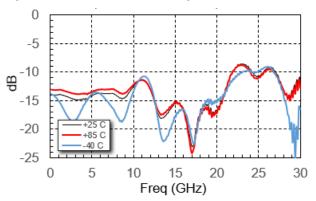


Input Return Loss (all states)

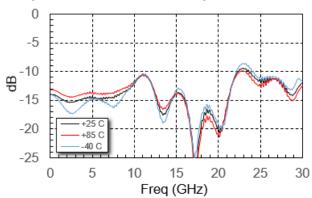


Output Return Loss (all states)

Input Return Loss vs. Temperature



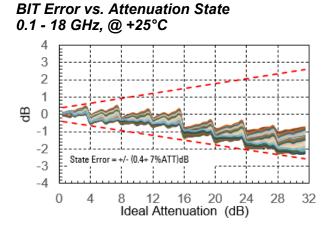
Output Return Loss vs. Temperature



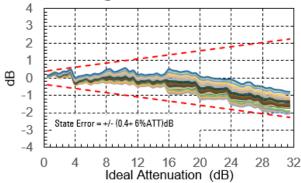
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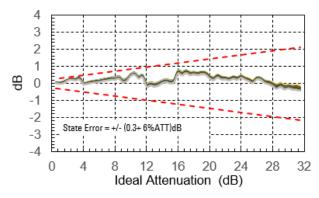




BIT Error vs. Attenuation State 18 - 26.5 GHz, @ +25°C

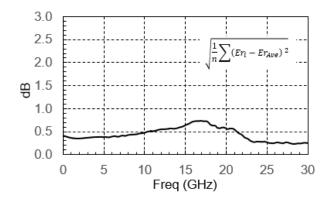


BIT Error vs. Attenuation State 26.5 - 30GHz, @ +25°C

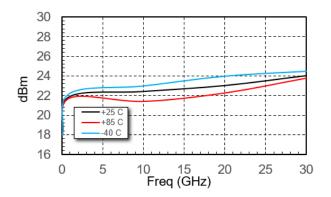


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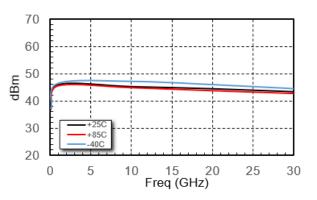
RMS Error vs. Frequency (mean)



Input 0.1dB Compression over Temp



Input IP3 over Temperature



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Modes of Operation Serial and Direct Parallel

Mode Truth Table⁸

P/S	LE	Mode
1	х	Serial
0	N/A	Direct Parallel

8. In the serial mode: D4, D5, and D6 should be tied to ground or to $V_{\text{CC}}.$

Direct Parallel Mode

The parallel mode is enabled when P/S is set low. In the direct parallel mode, the digital attenuator is controlled by the parallel control inputs directly. When P/S is set low, pins 22, 23, and 24 have the D3, D2, and D1 function.

Handling Procedures

Please observe the following precautions to avoid damage:

Static Sensitivity

These electronic devices are sensitive to electrostatic discharge (ESD) and can be damaged by static electricity. Proper ESD control techniques should be used when handling these HBM Class 1A devices.

Serial Mode

The serial control interface (SERI IN, CLK, LE, SER OUT) is compatible with the SPI protocol. SPI mode is activated when P/S is kept high. The 6-bit serial word must be loaded with the MSB first. After shifting in the 6 bit word, a rising edge on LE will set the digital attenuator to the desired state. While LE is high the CLK is masked to protect the data while implementing the change. SER OUT is SER IN delayed by 6 clock cycles.

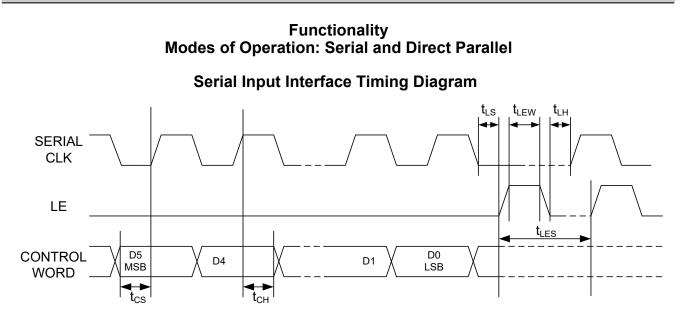
When P/S is low, the serial control interface is disabled. When P/S is set high, pins 22, 23, and 24 have the LE, CLK, and SER IN function.

In serial mode operation, the outputs will stay constant while LE is kept low.

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Serial Interface Timing Characteristics

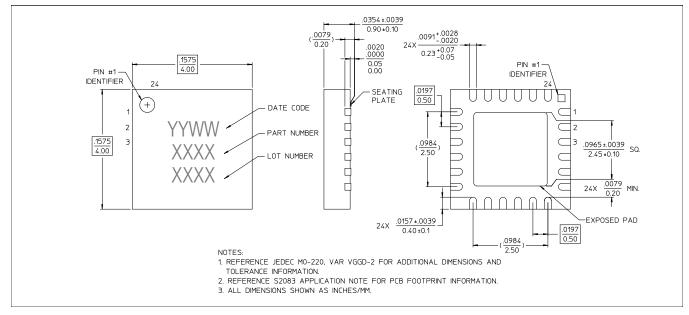
Symbol	Parameter	Units
t _{scк}	Min. Serial Clock Period	ns
t _{cs}	Min. Control Set-up Time	ns
t _{CH}	Min. Control Hold Time	ns
t _{LS}	Min. LE Set-up Time	ns
t _{LEW}	Min. LE Pulse Width	ns
t _{LH}	Min. Serial Clock Hold Time from LE	ns
t _{LES}	Min. LE Pulse Spacing	ns

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Lead Free 4 mm 24-Lead PQFN [†]



[†] Reference Application Note S2083 for lead-free solder reflow recommendations. Meets JEDEC moisture sensitivity level 1 requirements. Plating is 100% matte tin over copper.



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